# Chapter 1

# Vector spaces

In this chapter  $\Bbbk$  represents a field

# 1.1 Vector space

**Definition 1.1.** A vector space over  $\Bbbk$  is a non-empty set E endowed with two laws:

• an internal composition law called addition and denoted "+"

$$\begin{array}{cccc} +:E\times E & \longrightarrow & E\\ (x,y) & \longmapsto & x+y \end{array}$$

• an *external composition law* called multiplication by a scalar and denoted by "."

$$\begin{array}{cccc} \cdot: \Bbbk \times E & \longrightarrow & E \\ (\lambda, x) & \longmapsto & \lambda \cdot x \end{array}$$

such that:

- 1. (E, +) is a **commutative group**, where the neutral element is denoted by  $0_E$  and the symmetric of an element x of E will be denoted -x;
- 2. The external law must satisfy for all  $x \in E$  and  $\alpha, \beta \in \Bbbk$ :

$$\alpha \cdot (\beta \cdot x) = (\alpha \beta) \cdot x;$$

3. for all  $x, y \in E$  and  $\alpha, \beta \in \Bbbk$ :

$$(\alpha + \beta) \cdot x = \alpha \cdot x + \beta \cdot x;$$

4. for all  $x, y \in E$  and  $\alpha, \beta \in \Bbbk$ :

$$\alpha \cdot (x+y) = (\alpha \cdot x) + (\alpha \cdot y);$$

5.  $1_{k} \cdot x = x$ .

#### Elementary property:

Let E be a  $\Bbbk$  -vector space, then we have the following properties:

- $\forall x \in E, \ 0 \cdot x = 0_E$
- $\forall \alpha \in \mathbb{k}, \ \alpha \cdot 0 = 0_E$
- $\alpha \cdot x = 0_E \Leftrightarrow \alpha = 0_k$  or  $x = 0_E$ ;

**Example 1.1.**  $(\mathbb{R}, +, .)$  is a  $\mathbb{R}$ -vector space and  $(\mathbb{C}, +, .)$  is a  $\mathbb{C}$ -vector space.

**Example 1.2.** We consider  $\mathbb{k}^n$  the set of ordered sequences of n elements of  $\mathbb{k}$ , i.e.,  $(x_1, x_2, ..., x_n)$  with n being a positive integer. Let  $x = (x_1, x_2, ..., x_n)$  and  $x' = (x'_1, x'_2, ..., x'_n)$  two elements of  $\mathbb{k}^n$  and let  $\alpha \in \mathbb{k}$ , we set:  $x + x' = (x_1 + x'_1, x_2 + x'_2, ..., x_n + x'_n)$  and  $\alpha . x = (\alpha . x_1, \alpha . x_2, ..., \alpha . x_n)$ . Equipped with these two

laws, it is easy to verify that  $\mathbb{k}^n$  is a  $\mathbb{k}$  -vector space.

**Example 1.3.** The set  $V = F(\mathbb{R}, \mathbb{R})$  of functions from  $\mathbb{R}$  to  $\mathbb{R}$  equipped with the laws usual ways of adding functions, and multiplying a function by a scalar: (f+g)(x) = f(x) + g(x) and  $(\alpha.f)(x) = \alpha.f(x)$ , is a  $\mathbb{k}$  - vector space.

## 1.1.1 Vector subspace

In this part, E will denote a k-vector space.

**Definition 1.2.** A subset F of E is called a vector subspace on  $\Bbbk$  of E if

- (i)  $\emptyset \neq F \subset E$ ,
- (ii) F is a k-vector space.

There is another technique to show that a subset F of E is vector subspace.

**Theorem 1.1.** A subset F of E is called a **vector subspace** on  $\Bbbk$  of E if the following condition hold :

- (i)  $0_E \in F$ ;
- (*ii*)  $\forall x, y \in F, x + y \in F;$
- (*ii*)  $\forall \alpha \in \mathbb{k}, \forall x \in F, \ \alpha.x \in F.$

**Theorem 1.2.** Let F be a nonempty subset of E, the following assertions are equivalence :

- F is a vector subspace over k,
- *F* is stable for addition and for multiplication by a scalar .i.e
  ∀x, y ∈ F, x + y ∈ F; and ∀α ∈ k, ∀x ∈ F, α.x ∈ F.
- $\forall x, y \in F, \forall \alpha, \beta \in \mathbb{k}; \alpha.x + \beta.y \in F.$

**Example 1.4.** (1). E and  $0_E$  are vector sub-spaces of E.

(2).  $F = \{(x, y) \in \mathbb{R}^2 | x + y = 0\}$  is a vector subspace of  $\mathbb{R}^2$  over  $\mathbb{R}$  because,

- $0_E = 0_{\mathbb{R}^2} = (0,0) \in F \Rightarrow F \neq \emptyset$
- $\forall (x,y), (x',y') \in F, \forall \alpha, \beta \in \mathbb{R} : \alpha(x,y) + \beta(x',y') \in F \text{ i.e } (\alpha x + \beta x', \alpha y + \beta y') \in F$ we have

 $(x,y) \in F \Rightarrow x + y = 0$  and  $(x',y') \in F \Rightarrow x' + y' = 0$ 

$$\alpha x + \beta x' + \alpha y + \beta y' = \alpha (x+y) + \beta (x'+y') = \alpha (0) + \beta (0) = 0$$

Then  $\alpha(x, y) + \beta(x', y') \in F$ , so F is vector subspace of E.

3. The set  $F = \{(x, y) \in \mathbb{R}^2 | x - y + 1 = 0\}$  is not a vector subspace of  $\mathbb{R}^2$  because the zero vector  $0_{\mathbb{R}^2}$  does not belong to F.

### 1.1.2 Intersection and union of vector sub-spaces

**Proposition 1.1.** The intersection of two vector sub-spaces is a vector subspace.

Proof. Consider  $F_1$  and  $F_2$  two vector sub-spaces of E. First  $0_E \in F_1$ , because  $F_1$  is a vector subspace of E. Similarly,  $0_E \in F_2$ . Thus,  $0_E \in F_1 \cap F_2$  and  $F_1 \cap F_2$  is therefore not empty. Given  $x, y \in F_1 \cap F_2$  and  $\alpha, \beta \in \mathbb{k}$ , we then have  $\alpha x + \beta y \in F_1$  since  $F_1$  is a vector subspace of E. Similarly,  $\alpha x + \beta y \in F_2$ . Thus,  $\alpha x + \beta y \in F_1 \cap F_2$ . It follows that  $F_1 \cap F_2$  is a vector subspace of E.

**Lemma 1.1.** The intersection  $\bigcap_{i=1}^{n} F_i$  of vector subspaces of a vector space E is a vector subspace of E.

**Remark 1.1.** In general, the union of two vector sub-spaces is not a vector subspace. Indeed, if we consider  $E = \mathbb{R}^2$  and the two vector sub-spaces

$$D_1 = \{(x, y) \in \mathbb{R}^2 | y = 0\} \text{ and } D_2 = \{(x, y) \in \mathbb{R}^2 | x = 0\}.$$

Then  $D_1 \cup D_2$  is not a vector subspace of E. For example,  $(\frac{1}{2}, 0) + (0, \frac{1}{2}) = (\frac{1}{2}, \frac{1}{2})$  is the sum of an element of  $D_1$  and an element of  $D_2$ , but is not in  $D_1 \cup D_2$ .

## **1.2** Generating families, Free families, Basis

#### • Linear combination

**Definition 1.3.** For  $n \in \mathbb{N}^*$ , A linear combination of vectors  $u_1, u_2, ..., u_n$  of a k-vector space E, is a vector which can be written  $V = \sum_{i=1}^n \lambda_i u_i$ . The elements  $\lambda_1, \lambda_2, ..., \lambda_n \in \mathbb{k}$  are called **coefficients** of the linear combination. **Example 1.5.** In  $\mathbb{R}^3$ , the vector U = (3, 3, 1) is a linear combination of vectors (1, 1, 0) and (1, 1, 1) because U = (3, 3, 1) = 2(1, 1, 0) + (1, 1, 1)

- **Remark 1.2.** If F is a vector subspace of E, and  $u_1, u_2, ..., u_n \in F$ , then any linear combination  $\sum_{i=1}^n \lambda_i u_i$  is in F.
  - Let u<sub>1</sub>, u<sub>2</sub>, ..., u<sub>n</sub>, n vectors of a k-vector space E. One can always write 0<sub>E</sub> as a linear combination of these vectors, because it suffices to take all zero coefficients of the linear combination.
  - If n = 1, then  $V = \lambda_1 u_1$  we say that V is **colinear** with  $u_1$ .
  - In  $\mathbb{R}^2$ , the vector u = (2, 1) is not colinear with v = (1, 1).

#### Notation

Given the vectors  $u_1, u_2, ..., u_n$  of k-vector space E, we denote  $Vect(u_1, u_2, ..., u_n)$  or  $\langle u_1, u_2, ..., u_n \rangle$  the set of linear combination of  $u_1, u_2, ..., u_n$ . So we write :

$$\langle u_1, u_2, \dots, u_n \rangle = Vect(u_1, u_2, \dots, u_n) = \{ u \in E \mid \exists \lambda_1, \lambda_2, \dots, \lambda_n \in \mathbb{k}^n; u = \sum_{i=1}^n \lambda_i u_i \}$$

#### • Generating families

We consider a nonempty family  $A = (u_1, u_2, ..., u_n)$  of vectors of a k -vector space E with  $n \in \mathbb{N}^*$ .

**Definition 1.4.** We say that A generates E, or that it is generator of E if and only if  $Vect(u_1, u_2, ..., u_n) = E$ . In other words, any vector of E is a linear combination of the elements of A.

- Example 1.6.  $A = \{u_1 = (1,0,0), u_2 = (0,1,0), u_3 = (0,0,1)\}$  generates  $\mathbb{R}^3$ , because for all  $U = (x, y, z) \in \mathbb{R}^3$  we have: (x, y, z) = x(1,0,0) + y(0,1,0) + z(0,0,1)
  - Let u₁ = (1, 1, 1), u₂ = (1, 2, 3) two vectors of ℝ<sup>3</sup>
     We have:

$$(x, y, z) \in Vect(u_1, u_2) = \langle u_1, u_2 \rangle \Leftrightarrow (x, y, z) = \lambda_1(1, 1, 1) + \lambda_2(1, 2, 3) \Leftrightarrow x = \lambda_1 + \lambda_2, \ y = \lambda_1 + 2\lambda_2, \ z = \lambda_1 + 3\lambda_2$$

Then  $\{u_1, u_2\}$  generates  $\mathbb{R}^3$ 

#### • Free families

**Definition 1.5.** We say that A is **free** if and only if the null vector  $0_E$  is a linear combination of elements of A unique way. In other words:

 $\forall \lambda_1, \lambda_2, \dots, \lambda_n \in \mathbb{k}, \quad \sum_{i=1}^n \lambda_i u_i = 0_E \; \Rightarrow \; \lambda_1 = \lambda_2 = \dots, \lambda_i = 0_E.$ 

Example 1.7. The set  $A = \{u_1 = (1, 0, 1), u_2 = (0, 2, 2), u_3 = (3, 7, 1)\}$  is free Let  $\lambda_1, \lambda_2, \lambda_3 \in \mathbb{R}$ , we have  $\sum_{i=1}^n \lambda_i u_i = \lambda_1(1, 0, 1) + \lambda_2 0, 2, 2) + \lambda_3(3, 7, 1) = 0_{\mathbb{R}^3} \Rightarrow \lambda_1 = \lambda_2 = \lambda_3 = 0$ 

**Remark 1.3.** We can use the following expressions:

- If A is free then we also say that the vectors  $(u_1, u_2, ..., u_n)$  are linearly independent.
- If A is not free, we say that A is linked.
- A family of a single vector is **free** if and only if this vector is **non-zero**.
- Basis

**Definition 1.6.** We say that A is a **basis** of a vector space E if it is **free** and **generating**. In other words, every vector of E is a linear combination of the elements of A in a unique way. So we have:

$$\forall u \in E, \exists ! (\lambda_1, \lambda_2, ..., \lambda_n) \in \mathbb{k}^n \ u = \sum_{i=1}^n \lambda_i u_i$$

where  $\lambda_1, \lambda_2, ..., \lambda_n$  are called the **coordinates** of the vector u in this basis A.

## **1.3** Dimension of Vector spaces

#### finite type

**Definition 1.7.** A vector space is said to be of **finite type** if it admits a finite generating family. In other words: if a vector space is generated by a finite family of vectors, it is said to be of **finite type**.

**Theorem 1.3.** In a finite dimensional vector space E, all **basis** have the same number of elements. This number denoted dim(E) is called the **dimension** of E.

**Theorem 1.4.** Let A be a family of elements of E of finite dimension n. The following properties are equivalent:

- (i) A is a basis of E.
- (ii) A is free and generates E.
- (iii) A is free and cardinal(A) = n.

(v) A is the generator of E and cardinal(A) = n.

**Example 1.8.** The set  $A = \{u_1 = (1, 2), u_2 = (2, -1)\}$  generates  $\mathbb{R}^2$ . What can we conclude? To show that A is a generating family, we look for two real  $\lambda_1, \lambda_2$  such that: for all  $u = (x, y)in\mathbb{R}^2$ 

 $U = \lambda_1 u_1 + \lambda_2 u_2$ . After the calculation we will have  $\lambda_1 = \frac{1}{5}(x+2y), \lambda_2 = \frac{1}{5}(x-2y)$  Which means that A generates  $\mathbb{R}^2$ . On the other hand, it is clear that A is free, of cardinal 2, so A is a basis of  $\mathbb{R}^2$ .

- We deduce that in a vector space E, any free family (or generator) whose number of elements is equal to the dimension of E is a basis.

**Theorem 1.5.** Let F be a vector subspace of  $E - \Bbbk$  vector space, we have

- $dim(F) \le dim(E)$
- $dim(F) = dim(E) \Leftrightarrow E = F$

**Corollary 1.1.** (1)- Every vector space of finite type admits a finite basis, and all its bases have the same cardinality.

In a vector space of dimension n, we have:

- (2)- Any free family has at most n elements.
- (3)- Any generating family has at least n elements

## **1.3.1** Rank of finite family of vectors

**Definition 1.8.** Let E be a k-vector space and  $G = \{v_1, v_2, ..., v_m\}$  a family of m vectors of E. The **rank** of the family G noted rank(G) is the dimension of the vector subspace  $F = Vect(v_1, v_2, ..., v_m)$  generated by the vectors  $v_1, v_2, ..., v_m$  i.e, rank(G) = dim(F). or the largest number of linearly indepent vectors.

**Properties :** Let E be a k-vector space and  $G = \{v_1, v_2, ..., v_m\}$  a family of vectors of E. So we have:

- 1  $0 \leq rank(G) \leq m$ .
- 2 If dim(E) = n (finite), then  $rank(G) \le n$ .
- 3 rank(G) = m if and only if G is free.
- 4 rank(G) = 0 if and only if all vectors of G are zero.

**Example 1.9.** Let  $G = \{v_1 = (2,3), v_2 = (4,2), v_3 = (-3,4)\}$  be a family of the vector space  $\mathbb{R}^2$ . Determine the rank of G.

It is clear that  $v_2$  and  $v_3$  are linearly independent. On the other hand, by solving the linear system  $\alpha_1v_1 + \alpha_2v_2 + \alpha_3v_3 = 0$ , we get  $2v_1 - v_2 - v_3 = 0$ . The family G is therefore dependent. We deduce that  $Vect(v_1, v_2, v_3) = Vect(v_1, v_2)$ . So rank(G) = 2.

# 1.4 Complementary vector subspace

#### **1.4.1** • Sum of two vector sub-spaces

**Definition 1.9.** Let  $F_1$  and  $F_2$  be two vector sub-spaces of a k-vector space E. We call sum of  $F_1$  and  $F_2$  the set noted  $F_1 + F_2$ , vectors which are the sum of a vector of  $F_1$  and a vector of  $F_2$ :

$$F_1 + F_2 = \{ u : u = u_1 + u_2, u_1 \in F_1, u_2 \in F_2 \}.$$

**Remark 1.4.** We can characterize the vectors u of the sum  $F_1 + F_2$ , by:

$$u \in F_1 + F_2 \iff \exists (u_1, u_2) \in F_1 \times F_2, \ u = u_1 + u_2$$

**Proposition 1.2.** Let  $F_1$  and  $F_2$  be two vector sub-spaces of a k-vector space E.

- (1)-  $F_1 + F_2$  is a vector subspace of E.
- (2)-  $F_1 + F_2$  is the smallest vector subspace of E containing both  $F_1$  and  $F_2$ .
- Proof. (1) Consider  $F_1$  and  $F_2$  be two vector sub-spaces of E. First  $0_E \in F_1$  because  $F_1$  is a vector subspace of E. Similarly,  $0_E \in F_2$  Thus,  $0_E = 0_E + 0_E \in F_1 + F_2$  and  $F_1 + F_2$  is therefore not empty. Let  $x, y \in F_1 + F_2$  and  $\alpha, \beta \in \mathbb{k}$ . Since  $x \in F_1 + F_2$ , there are  $x_1 \in F_1$  and  $x_2 \in F_2$  such that :  $x = x_1 + x_2$  so  $\alpha x = \alpha(x_1 + x_2) = \alpha(x_1) + \alpha(x_2) \in F_1 + F_2$ , because  $\alpha(x_1) \in F_1$  and  $\alpha(x_2) \in F_2$ . Similarly for  $y \in F_1 + F_2$ , we get  $\beta y = \beta(y_1 + y_2) = \beta(y_1) + \beta(y_2) \in F_1 + F_2$ , because  $\beta(y_1) \in F_1$  and  $\beta(y_2) \in F_2$  with  $y = y_1 + y_2$ . It follows that  $\alpha x + \beta y = (\alpha x_1 + \beta y_1) + (\alpha x_2 + \beta y_2) \in F_1 + F_2$ .
  - (2) We first show that the set F<sub>1</sub>+F<sub>2</sub> contains both F<sub>1</sub> and F<sub>2</sub>. Indeed, any element u<sub>1</sub> ∈ F<sub>1</sub> is written u<sub>1</sub> = u<sub>1</sub> + 0<sub>E</sub> with u<sub>1</sub> belonging to F<sub>1</sub> and 0<sub>E</sub> belonging to F<sub>2</sub>, because F<sub>2</sub> is a vector subspace of E. u<sub>1</sub> belongs to F<sub>1</sub> + F<sub>2</sub>. The same for an element of F<sub>2</sub>. Now we show that if H is a vector subspace containing F<sub>1</sub> and F<sub>2</sub>, then F<sub>1</sub> + F<sub>2</sub> ⊂ H. As F<sub>1</sub> ⊂ H. we therefore have, if u<sub>1</sub> ∈ F<sub>1</sub> then in particular u<sub>1</sub> ∈ H. Similarly, if u<sub>2</sub> ∈ F<sub>2</sub>

then  $u_2 \in H$ . Since H is a vector subspace, then  $F_1 + F_2 \subset H$ .

**Example 1.10.** Determine F + G where F and G be two vector sub-spaces of  $\mathbb{R}^3$   $F = \{(x, y, z) \in \mathbb{R}^3 : y = z = 0\}$  and  $G = \{(x, y, z) \in \mathbb{R}^3 : x = z = 0\}$ any element w of F + G is written w = u + v where u an element of F and v an element of G. For all  $u \in F$  there exist  $x \in \mathbb{R}$  such that u = (x, 0, 0) and for all  $v \in G$ , there exist  $y \in \mathbb{R}$  such that v = (0, y, 0), so w = u + v = (x, y, 0) is the sum of (x, 0, 0) and (0, y, 0). Conversely, all element w = (x, y, 0) = (x, 0, 0) + (0, y, 0) is a sum of an element of F and an element of G. Then  $F + G = \{(x, y, z) \in \mathbb{R}^3 : z = 0\}$  **Proposition 1.3.** 4 (Grassmann formula). Let E be  $\mathbb{k}$ - vector space of finite dimension,  $F_1$  and  $F_2$  be two vector sub-spaces of E, then :

$$dimE = dimF_1 + dimF_2 - dim(F_1 \cap F_2)$$

For the existence of additional sub-spaces in finite dimension, the incomplete basis theorem says that in a finite dimensional vector space, any free family can be completed into a basis of the space. We immediately deduce the existence of supplementary ones.

### **1.4.2** • Direct sum of two vector sub-spaces

**Proposition 1.4.** Let  $F_1$  and  $F_2$  be two vector sub-spaces of E. We say that the sum  $F_1 + F_2$ is **direct** if any vector of  $F_1 + F_2$  decomposes **uniquely** as the sum of an element of  $F_1$  and an element of  $F_2$ 

 $E = F_1 \oplus F_2$  then  $\forall w \in E$ ,  $\exists ! \ u \in F_1$   $\exists ! \ v \in F_2$  such that : w = u + v

Notation When  $F_1$  and  $F_2$  are in direct sum, we write  $F_1 + F_2 = F_1 \oplus F_2$ .

**Definition 1.10.** Let  $F_1$  and  $F_2$  be two vector sub-spaces of E. We say that the sum  $F_1 + F_2$ is **direct**  $(E = F_1 \oplus F_2)$  if and only if

- $F_1 \cap F_2 = 0_E$
- $E = F_1 + F_2$

**Corollary 1.2.** Let E be  $\Bbbk$ - vector space of finite dimension, then the following conditions are equivalent.

- (1)  $E = F_1 \oplus F_2$
- (2)  $F_1 \cap F_2 = 0_E$  and  $dimE = dimF_1 + dimF_2$
- (3)  $E = F_1 + F_2$  and  $dimE = dimF_1 + dimF_2$

#### Remark 1.5.

- (1) If F and G are in direct sum, we say that F and G are supplementary sub-spaces in E.
- (2) To say that an element can be uniquely expressed as the sum of an element in F and an element in G means that an element w = u + v where  $u \in F, v \in G$  and w = u' + v' where  $u' \in F, v' \in G$  then u = u' and v = v'.
- (3) In general, there is no uniqueness of the supplementary. In other words, for a vector subspace F<sub>1</sub> of a k-vector space E, we can find many different supplementary F<sub>2</sub> such as F<sub>1</sub> ⊕ F<sub>2</sub> = E.
- **Example 1.11.** (1)- Let  $F = \{(x,0) \in \mathbb{R}^2 | x \in \mathbb{R}\}$  and  $G = \{(0,y) \in \mathbb{R}^2 | y \in \mathbb{R}\}$  two subspaces of  $\mathbb{R}^2$ .  $\mathbb{R}^2 = F \oplus G$  because  $F \cap G = \{0_{\mathbb{R}^2}\}$  and if any vector of  $\mathbb{R}^2$  decompose uniquely as (x,y) = (x,0) + (0,y), then  $\mathbb{R}^2 = F + G$ ,
- (2)- We show that there is no uniqueness of the supplementary of a sub-space. Let's keep  $F = \{(x, 0) \in \mathbb{R}^2 / x \in \mathbb{R}\}$  and  $G' = \{(x, x) \in \mathbb{R}^2 / x \in \mathbb{R}\}$ we have  $\mathbb{R}^2 = F \oplus G'$ show that  $F \cap G = \{0_{\mathbb{R}^2}\} = (0, 0)$ . If  $(x, y) \in F \cap G'$ , then  $(x, y) \in F$  so y = 0 and  $(x, y) \in G$  so x = y then (x, y) = (0, 0). Show that  $\mathbb{R}^2 = F + G'$ Let  $u = (x, y) \in \mathbb{R}^2$ . Find  $v \in F$  and  $w \in G'$  such that u = v + w  $(x_1, y_1) \in F$  so  $y_1 = 0$  and  $(x_2, y_2) \in G'$  then  $x_2 = y_2$ . It's about finding  $x_1$  and  $x_2$  such that  $(x, y) = (x_1, 0) + (x_2, x_2)$  then  $(x, y) = (x_1 + x_2, x_2) / x = x_1 + x_2, y = x_2$ Finally (x, y) = (x - y, 0) + (y, y)

**Exercise 1.** Let  $\mathbb{R}^3$  be the vector space on the field  $\mathbb{R}$ , G = [(1,1,0), (0,0,1), (1,1,1)], be a vector subspace of  $\mathbb{R}^3$  and let the set F be defined as :  $F = \{(x,y,z) \in \mathbb{R}^3/2x + y - z = 0\}$ 

1. Show that F is a vector subspace of  $\mathbb{R}^3$ .

- 2. Find a basis for each of : F, G,  $F \cap G$ , F + G, and give their dimensions.
- 3. Is  $\mathbb{R}^3 = F \oplus G$ ?